

20 1 Introduction

21 Given its important role for economies and societies, the assessment, preventive conservation and
22 maintenance of historical masonry structures continue to stand as major priorities of the overall political
23 strategy at the European level. In this context, the earthquake protection of historical masonry structures
24 assumes particular relevance because of their non-negligible seismic vulnerability. The tangible and
25 intangible value of this type of ancient buildings is further enhanced by the artworks located therein,
26 such as sculptures, paintings and frescos, among others. This means that when a disaster involves
27 historical centres, it is likely that buildings, as well as artworks, are damaged, producing: i) a physical
28 loss of artistic and historical materials; ii) an immaterial loss of memory and cultural identity for the
29 people to whom that legacy "belongs"; and iii) difficulties in the action of the Civil Protection in
30 assisting the population affected by the disaster [1].

31 In this regard, to preserve historical masonry structures, several researchers focused on implementing
32 advanced computational modelling strategies. The overall classification of these tools is mainly made
33 between numerical and analytical approaches [2,3].

34 Numerical approaches are typically implemented in the Finite Element Method (FEM) [4–10] or
35 Discrete Element Method (DEM) [11–17] frameworks. Such approaches model the masonry material
36 using different representation scales, i.e., equivalent continuum, macro-blocks, or discrete
37 representations. FEM allows more versatile application as masonry can be represented either through a
38 homogeneous equivalent media (designated macro-modelling) or by a discrete representation of units
39 and joints (designated as simplified micro-modelling) [6,18]. DEM is well suited for masonries (both
40 dry- and mortared joints [19–21]), and focuses in non-homogeneous material representations. The
41 computational procedure of DEM provides a great advantage to consider the complex geometrical
42 features of masonry in structural analysis [21–23]. Typically, in a DEM-based discontinuum analysis,
43 masonry constructions are represented via a system of distinct polyhedral blocks that can interact based
44 on the point contact hypothesis [24,25]. The mechanical interaction among adjacent blocks is
45 formulated through the prescribed contact stress-displacement laws with different linear or nonlinear
46 behaviour. Rigid and/or deformable blocks may be used depending on the research question and the
47 expected outcomes from the numerical model, also considering a compromise between computational

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48 cost and accuracy. As shown by various studies in the literature, DEM offers a wide range of solutions
49 to simulate regular and irregular, discontinuous medium subjected to quasi-static, dynamic, or coupled
50 thermo-mechanical loadings from mesoscale to macro-scale [22,26–29].

51 Nonetheless, in addition to the significant amount of data needed to characterise the nonlinear response
52 of materials, the analysis can be time-consuming and computationally expensive, particularly when the
53 objective is to estimate the ductility level of the structure (as required in design codes for performance
54 based seismic assessment). Despite their reliability, the computational efficiency of the available
55 numerical methods is rarely compatible with the need to have a rigorous real-time post- or pre-
56 earthquake assessment [30]. Hence, several research groups have been developing alternative modelling
57 approaches and practical tools to decrease the computational cost of nonlinear static and dynamic
58 analyses [31–34].

59 When a disaster happens, the structural safety assessment of a huge number of constructions, including
60 building aggregates, churches and other monuments, must be performed in a short time. In addition,
61 most professionals lack the necessary knowledge to use adequately advanced simulation tools. Finally,
62 the requirements of using these advanced tools are, often, not in line with the available time and budget.
63 Therefore, despite the extraordinary computational power available thanks to state of the art CPU
64 processors and advanced software, often structural engineers adopt analytical approaches based on limit
65 analysis (LA) theorems. These have the great advantage of requiring only a few material properties but,
66 inevitably, rely on a very simplified material model [35–40]. In literature, LA has been formulated at
67 both macro and micro scales. Micro scale LA formulations account for a unit by unit description with
68 an introduction of interfaces that represent masonry joints. In [41], a formal procedure for finding the
69 limit load of any structure formed from rigid blocks is given. In this formulation, the limit of the shear
70 force at a block interface was computed according to Coulomb's friction theory. In [42], the computation
71 of the load multiplier of discrete rigid block systems, characterised by frictional (non-associative) and
72 tensionless contact interfaces, was formulated and solved through a Mathematical Program with
73 Equilibrium Constraints (MPEC). Similarly, in [43], a simple iterative procedure which involves the
74 successive solution of linear programming sub-problems is adopted. Recently, several research groups

1 75 proposed customised computer program interfaces, which can also account for 3D rigid block
2 76 assemblages [44,45].

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4 77 One can note that micro LA requires unit by unit representation, which is still a challenging task,
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6 78 particularly when non-periodic or rubble masonry patterns affect the behaviour of structures under
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8 79 investigation. For this reason, macro scale LA is considered as a practical and useful tool for the rapid
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10 80 and engineering assessment of the collapse load of masonry structures[46], and national and
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12 81 international standards suggest its use [47]. In this framework, following post-earthquake damage
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14 82 surveys carried out after the Irpinia and Syracuse earthquakes in Italy, an abacus of local failure
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16 83 mechanisms was compiled [48]. In this framework, algorithms able to find the most reasonable collapse
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18 84 mechanisms into user-defined analysis routines have been implemented [49–52]. In [53], a numerical
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20 85 procedure for the LA of 2D masonry structures subject to arbitrary loading was developed. Similarly,
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22 86 in the framework of LA methods, other authors have proposed meta-heuristic approaches (i.e., Genetic
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24 87 Algorithms) as a tool to explore the value of loads associated with considered collapse mechanisms
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26 88 [54]. In [50], a simplified procedure for the prediction of the collapse load and the failure mechanism
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28 89 of in-plane loaded masonry walls was proposed, by taking into consideration frictional resistance.
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30 90 Recently another study upgraded this procedure in order to account for the actual frictional resistance
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32 91 [55]. However, the adopted formulation accounts only for regular masonry patterns.

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34 92 Indeed, the literature survey underlines the lack of macro LA formulation accounting for non-periodic
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36 93 or rubble masonry patterns. This is mainly due to the difficulties in evaluating the actual frictional
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38 94 resistance generated when irregular patterns affect masonry walls. The most rational solution to cover
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40 95 this gap is to refer to studies developing geometric masonry quality indexes to assess the quality of the
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42 96 masonry arrangements [56]. Some of these studies found useful correlations with the mechanical
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44 97 parameters [57], such as compressive strength, shear strength and elastic modulus. However, no studies
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46 98 correlate such quality indexes with the actual capacity of the irregular masonry pattern to produce in-
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48 99 plane frictional resistance.

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51 100 In order to address this knowledge gap, the present study aims to implement and validate a new theory
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53 101 for the computation of the frictional resistance involved in the in-plane sliding-rocking mechanism
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102 suitable for non-periodic and rubble masonry patterns. The proposed theory is integrated within the
103 framework of the upper-bound theorem of LA [52,55], with the methodology detailed next:

- 104 1. Develop a universal equation to assess the crack inclination upper threshold that characterises
105 masonry patterns when the structures are affected by the in-plane sliding-rocking failure
106 mechanisms.
- 107 2. Implement the macro-block LA formulation within a Rhino 3D + Grasshopper [58,59] plugin. The
108 plugin is using Python programming language. As an output, the tool provides the horizontal load
109 multiplier and the geometry of the failure mechanism.

110 The results obtained by the macro-block LA are validated against a detailed DEM model. Horizontal
111 load multipliers are compared with the expected failure mechanism for several wall configurations.

112 The novelties of the study are twofold: i) identification of a frictional resistance law that accounts for
113 irregular masonry patterns; and ii) useful guidelines for researchers and practitioners on the use of
114 macro-block LA.

115 The paper is divided as follows. Section 2 presents the macro-block LA formulation for in-plane sliding
116 rocking mechanism. In Section 3 the proposed formulation to compute crack inclination upper threshold
117 is analytically developed. Section 4 integrates of the proposed formula within a macro-block upper
118 bound LA formulation. Section 5 describes the DEM adopted as a reference for the validation of the
119 LA tool. Section 6 is devoted to validate the formulation through real and artificial case studies. Finally,
120 relevant conclusions are drawn in Section 7.

121 **2 Overview of existing macro-block formulation for the in-plane sliding-rocking failure** 122 **mechanism**

123 The in-plane sliding-rocking failure mechanism of unreinforced masonry structures, through macro-
124 block LA, has been extensively investigated in the literature [50,52,55,60]. As shown in Figure 1, the
125 sliding-rocking mechanism is pre-defined, and the equation of equilibrium can be formulated by means
126 of the virtual work principle in which the only unknown is the horizontal load multiplier. The external
127 virtual work contains both the overturning as well as the stabilising works performed by the inertial
128 forces, whereas the internal work is derived from the friction force at contact interfaces (Figure 1):

$$\begin{aligned} \delta W_{ext} &= \lambda \cdot W_{OBC} \cdot \delta_{O,OBC} - W_{OBC} \cdot \delta_{S,OBC} \\ \delta W_{int} &= F_{real} \cdot \delta_{S,f} \end{aligned} \quad (1)$$

where W_{OBC} is the inertial force arising from the self-weight of the macro-block OBC, $\delta_{O,OBC}$ and $\delta_{S,OBC}$ are the virtual overturning and stabilising displacements of the centre of gravity of the macro-block, and F_{real} is the frictional resistance generated by the wall. The formulation reported in Eq. (1) may be easily generalised to account for possible overload and a transverse façade that collapses out-of-plane; in this case, the reader can refer to [31,55].

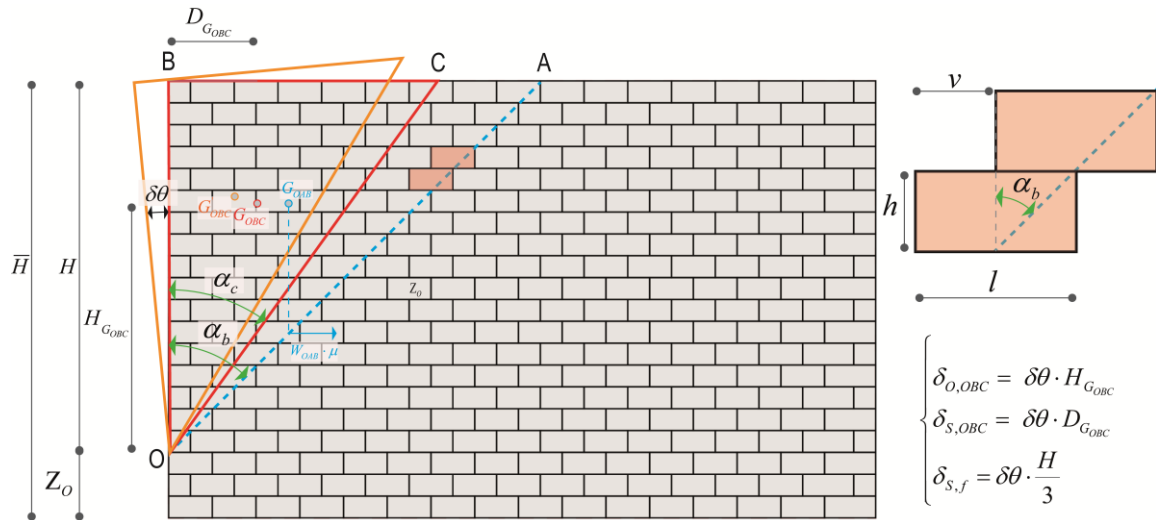


Figure 1: Kinematic description of the siding-rocking mechanism for an in-plane shear wall.

Regarding the internal work, it is worth remarking that the evaluation of the frictional resistance is not an easy task for masonry constituted by a regular or a non-periodic masonry pattern since it is difficult to estimate the number of active sliding interfaces along the generic crack. When pure sliding occurs, the frictional resistance may be easily computed accordingly to Coulomb's law as the product weight of the triangle OAB by the frictional coefficient μ [55], where the OAB is the macroblock identified by the maximum admissible crack line orientation. However, failure mechanisms often involve mix-mode sliding-rocking with consequently uplifting of the blocks that reduce the number of the bed joints in full contact. In order to take into consideration this phenomenon and to compute the actual frictional resistance, a proposal was made in [55] to compute the actual value of the frictional resistance for the moving part of the wall as a weighted value as a function of the inclinations of the crack line. This is given by:

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$$F_{real} = W_{OAB} \cdot \mu \cdot \left(1 - \frac{\alpha_c}{\alpha_b} \right) \quad (2)$$

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4 149 where α_c is the actual crack inclination and α_b is the crack inclination upper threshold (which depends
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6 150 on the geometry of the block):

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$$\tan(\alpha_b) = \frac{v}{h} \quad (3)$$

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12 152 Here, v and h are half-width and height of the unit blocks, respectively.

13 153 Hence, the horizontal load multiplier can be evaluated by equating external and internal virtual work
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15 154 and solving for λ . According to the upper-bound theorem of the LA, the computation of the horizontal
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17 155 load multiplier requires the solution of a constrained minimisation problem in which the parameters
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19 156 defining the failure mechanism's geometry, i.e., α_c and Z_o , are adopted as variables to explore all the
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21 157 panorama of possible solutions:

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26 minimise: λ
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28 158 subject to: $Z_o \leq \bar{H}$ (4)
29 $\alpha_c \leq \alpha_b$
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32 159 where Z_o is the height position of the pivot point and \bar{H} is the total height of the wall.

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34 160 One should note that the parameter Z_o only plays a role in case of overload or presence of a transverse
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37 161 façade [52].

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40 162 **3 Frictional resistance definition for different masonry typologies**

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42 163 It is worth noting how, despite the good accuracy of both horizontal multiplier and geometry of the
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44 164 failure mechanisms, the analytical formulation defined in Eq. (1)-(4) may only be adopted for regular
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46 165 assemblages of same size units, strongly limiting the field of applications of the macro-block LA.

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49 166 In order to make the aforementioned analytical formulation suitable for masonry walls composed of
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51 167 non-periodic patterns, the contribution arising from the definition of the frictional resistance must be
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53 168 reformulated. The challenge is to avoid Eq. (3) dependency on the block aspect ratio and propose a
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55 169 procedure based on the inspection of a representative masonry pattern window (RMPW) to define
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170 specific masonry quality indexes that serve as engineering parameters to define the crack inclination
 171 upper threshold α_b for different masonries, i.e., from regular to rubble.

172 **Remark 1**

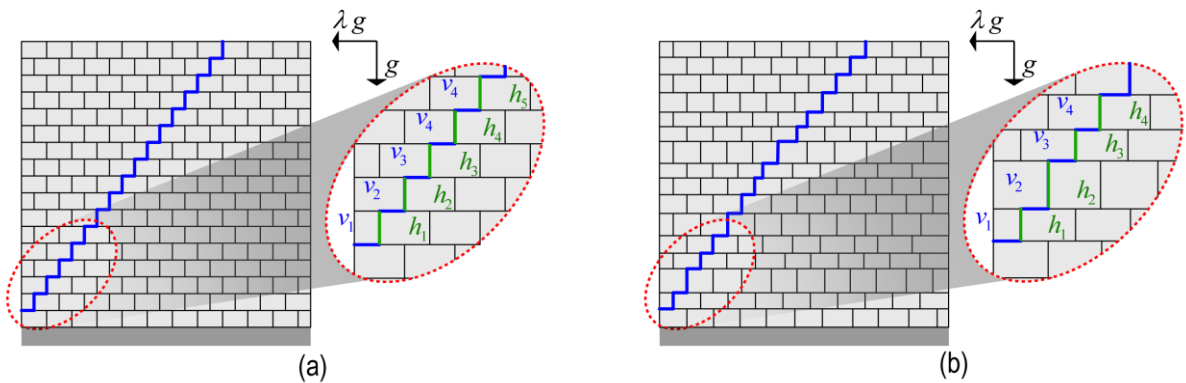
173 It is well known that to characterise/classify masonry patterns, one can focus on the definition of RMPW
 174 and compute masonry quality indexes and find their correlation with specific properties of the masonry
 175 macro behaviour [56,57].

176 **3.1 Regular and non-regular coursed squared masonries**

177 Figure 2 represents two in-plane shear walls constituted by regular or non-regular coursed squared
 178 masonries, subjected to horizontal inertial forces generating the sliding-rocking mechanism. The blu
 179 traced lines represent the identification of the crack inclination upper thresholds. In order to compute
 180 α_b , one has to compute the sums of the horizontal and vertical lines defined by the blu polyline,
 181 respectively and perform their ratio:

$$182 \tan(\alpha_b) = \frac{\sum_{i=1}^{n_c} v_i}{\sum_{i=1}^{n_c} h_i} \quad (5)$$

183 n_c is the number of courses, v_i and h_i are the horizontal interface' length and height of the unit blocks
 184 traced at the specific course, respectively.



185 Figure 2: In-plane shear wall: (a)Regular Pattern; (b) Non-Regular Pattern

186 Eq. (5) is valid for both regular (Figure 2a) and non-regular coursed squared masonries (Figure 2b),
 187 with the only difference that in the case of regular masonry, the evaluation of α_b only depends by the
 188 knowledge of the unit aspect ratio, since all the units have equal v and h (see Eq. (3)).

190 Inspired by Remark 1, instead of computing the crack inclination upper thresholds referring to the entire
 191 wall, it is here proposed to refer to an RMPW and calculate α_b accordingly:

$$192 \quad \tan(\alpha_b) = \frac{\sum_{i=1}^{n_c} v_i}{\sum_{i=1}^{n_c+1} h_i} \quad (6)$$

193 It is worth remarking that, in this case, n_c refers to the number of courses inside the RMPW.

194 At this stage, the blu traced line inside the RMPW (see Figure 3a first column), can be adopted in order
 195 to define a masonry quality index.

196 Such a masonry index (M_l^{UR}) is the ratio between the length of the blu line traced only through mortar
 197 joints following the structured path UP-RIGHT (v_l^{UR}) and the height of the RMPW (H_w) reading to:

$$198 \quad M_l^{UR} = \frac{v_l^{UR}}{H_w} \quad (7)$$

199 However, such a path could be not practical in some cases since it might require a very wide RMPW to
 200 connect the upper and the lower edges. Therefore, within the scope to make such a formulation more
 201 appealing for real case studies, and consequently taking into account that in some situations, it is
 202 necessary the removal of the plaster in order to inspect the masonry pattern, an alternative masonry
 203 index, i.e., following a structured path UP-RIGHT-UP-LEFT, is proposed (see Figure 3a second
 204 column):

$$205 \quad M_l^{URUL} = \frac{v_l^{URUL}}{H_w} \quad (8)$$

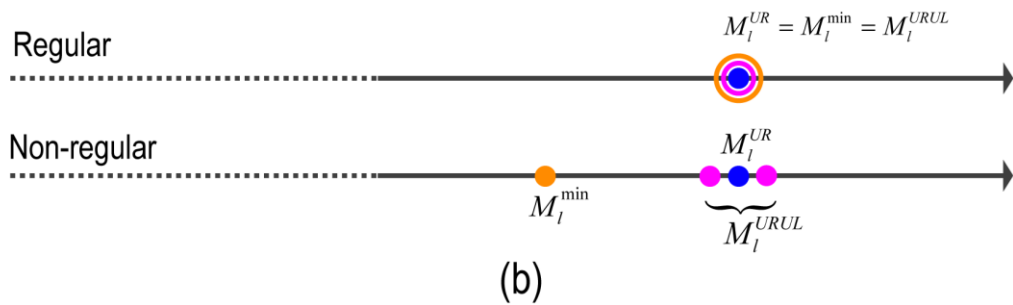
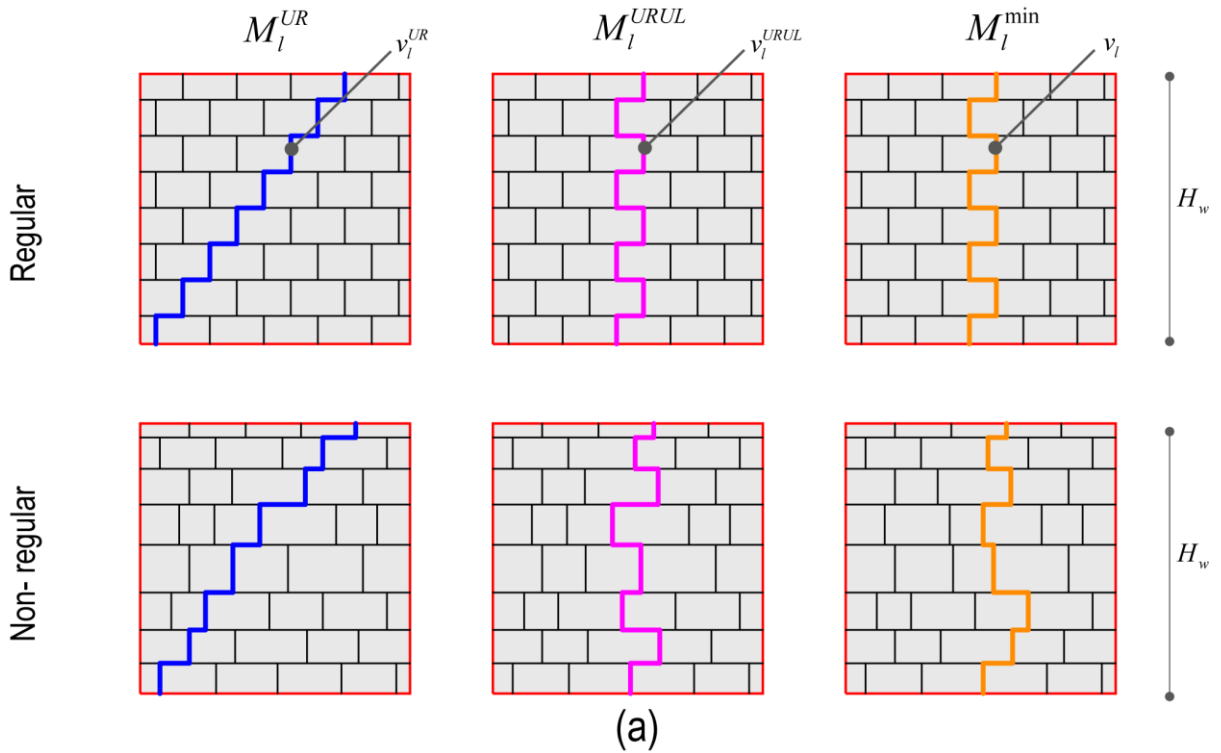
206 **Remark 2**

207 M_l^{UR} and M_l^{URUL} are masonry indexes here defined. When regular masonry characterises the structure
 208 under investigation, M_l^{URUL} provides the same evaluation than M_l^{UR} as well as that of the lines of the
 209 minimum trace (M_l^{\min}), as defined in [56,57] (see Figure 3a third column).

210 **Remark 3**

211 On the contrary, when the masonry pattern is coherent with Figure 2b, the use of the line of minimum
 212 trace, will provide a lower value with respect to M_l^{UR} , since the algorithm will search at each node the

213 shortest path to connect the upper and lower edges of the RMPW. Instead, the structured path UP-
 214 RIGHT-UP-LEFT (M_l^{URUL}) removes the underestimation generated by the use of the classical
 215 definition of the line of minimum trace (M_l^{\min}), providing an assessment very close to M_l^{UR} . Since
 216 both paths, i.e., UP-RIGHT-UP-LEFT and UP-RIGHT are pre-assigned, when the algorithm has to
 217 trace along the horizontal direction, there is a 50% chance of following the shortest or longest side
 218 resulting in $M_l^{UR} \simeq M_l^{URUL}$, in the case of appropriate number of courses are considered.



221 Figure 3: (a) Graphical interpretations of the lines of vertical trace (M_l^{UR} , M_l^{URUL} , M_l^{\min}); (b) Synoptic
 222 representation of values assumed by the line of vertical traces for regular and non-regular patterns.

223 In order to clarify these remarks, a synoptic representation of value assumed by M_l^{URUL} and M_l^{\min} with
 224 respect to the reference corresponding to the structured path UP-RIGHT (M_l^{UR}), for regular and non-
 225 regular coursed squared masonry, is represented in Figure 3b.

226 Referring to both regular and non-regular patterns, M_l^{URUL} can be defined with the following equation:

$$M_l^{URUL} = \frac{\sum_{i=1}^{n_c} v_i}{\sum_{i=1}^{n_c+1} h_i} + 1 \quad (9)$$

228 where n_c is the number of courses, v_i and h_i are the horizontal interface' length and height of the unit
 229 blocks traced at the specific course.

230 Therefore, by assuming the equivalence between M_l^{URUL} and M_l^{UR} (see Figure 3b) it is possible to
 231 substitute Eq. (9) into Eq. (6) and solve for $\tan(\alpha_b)$:

$$\tan(\alpha_b) = (M_l^{URUL} - 1) \quad (10)$$

3.2 Rubble masonry

234 When the masonry has a rubble pattern, it is not possible to follow a structured path, i.e., UP-RIGHT-
 235 UP-LEFT or UP-RIGHT, since clear horizontal and vertical joints cannot be identified. Hence,
 236 whenever the masonry pattern appears chaotic, i.e., with blocks having various shapes and sizes and no
 237 evidence of horizontal courses, M_l^{\min} should be adopted in order to generate an analytical relationship
 238 between the masonry pattern typology and the crack inclination upper threshold. To accomplish the
 239 latter, for the specific RMPW, M_l^{\min} is assessed and then adopted to identify an equivalent regular
 240 masonry pattern, in which the equivalence is defined by assuming a regular pattern characterised by the
 241 same value of M_l^{\min} (Figure 4). As a consequence, the crack inclination upper threshold defined in Eq.
 242 (10), is reformulated by replacing M_l^{URUL} with M_l^{\min} :

$$\tan(\alpha_b) = (M_l^{\min} - 1) \quad (11)$$

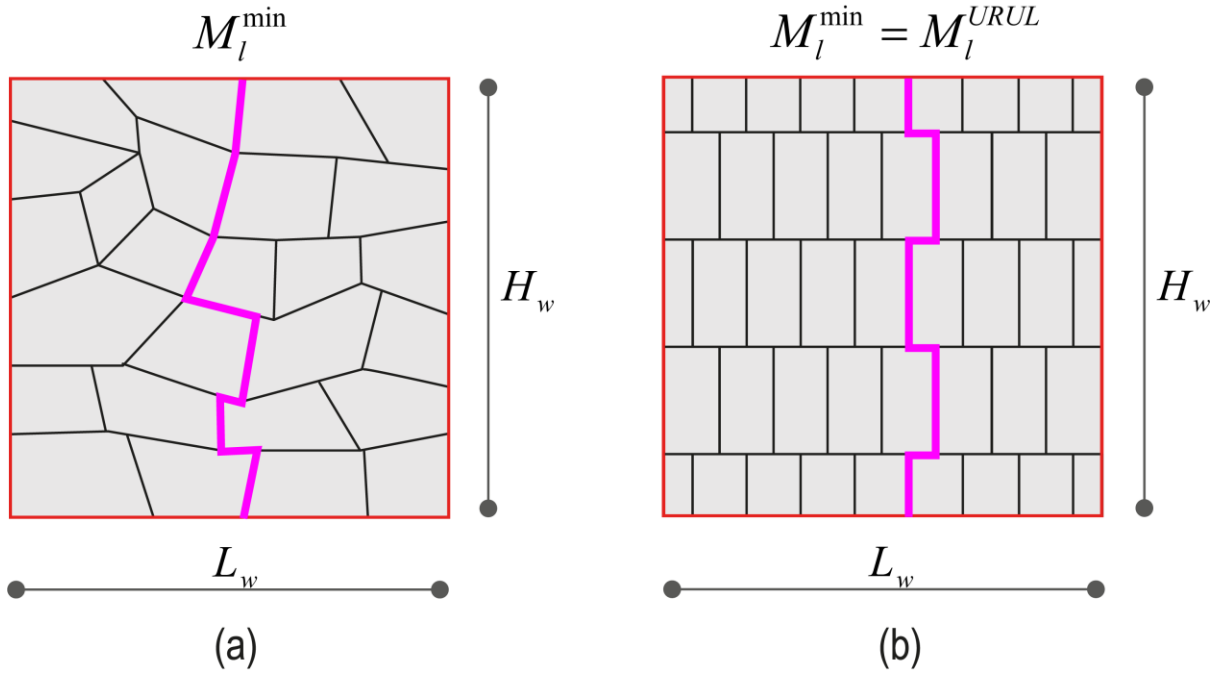


Figure 4: Equivalence between rubble (a) and regular (a) patterns expressed in terms of M_l^{\min}

It is worth noting that the equivalence represented in Figure 4 is developed considering that the masonry courses are perfectly horizontal (Figure 4b), which is the ideal condition for unreinforced masonry structures providing uniform contact surfaces between units.

Remark 4

According to field and experimental observations reported in [56], the absence of horizontal joints influences masonry pattern capacity to generate frictional resistance, reducing the crack inclination upper threshold.

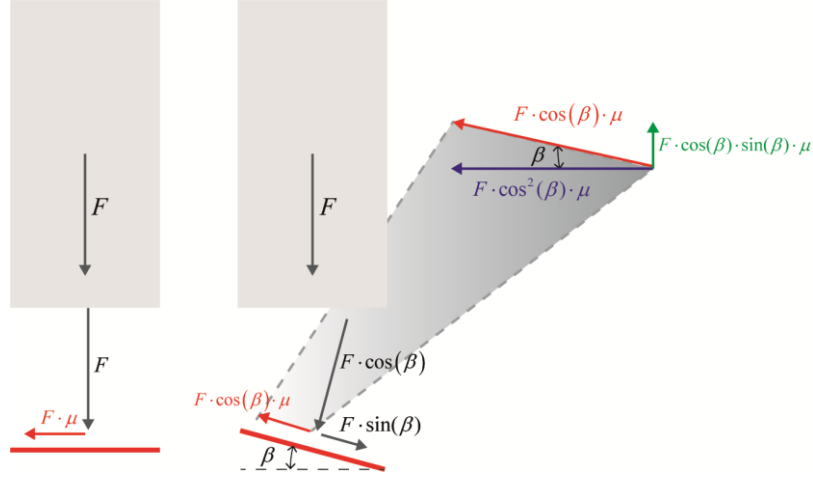
In order to better explain this concept, in Figure 5 the frictional force is computed for the same column of material for both a horizontal interface and one characterised by an inclination of β . When the interface is inclined, the horizontal component of the frictional resistance, according to Coulomb's law, is equal to $F \cdot \cos^2(\beta) \cdot \mu$, whereas, for the horizontal interface, it is equal to $F \cdot \mu$ (Figure 5).

Referring again to the Coulomb's frictional resistance generated by the in-plane wall depicted in Figure 1, one can note that the following expression defines the weight of the triangle OAB:

$$W_{OAB} = \frac{(\bar{H} - Z_o)^2}{2} \cdot \tan(\alpha_b) \cdot t_w \cdot \gamma \tag{12}$$

where t_w is the thickness of the in-plane wall, and γ is the specif weight of the masonry.

261 Keeping in mind what is represented in Figure 5, in case of inclined interfaces, the user has to consider
 262 the horizontal component of the frictional resistance that requires the knowledge of the term $\cos^2(\beta)$.
 263 Hence, such a term might be introduced into Eq.(12) via the definition of the crack inclination upper
 264 threshold α_b , which his definition is the aim of the present formulation.



265 Figure 5: Computation of the horizontal component of the frictional resistance in horizontal or inclined interfaces.

267 The horizontal line of minimum trace (M_{ol}) is the ratio between the distance to connect two points
 268 located on the left and right boundaries of a given RMPW, passing only through joints and the horizontal
 269 distance between the two points (Figure 6a):

$$270 \quad M_{ol} = \frac{v_{ol}}{L_w} \quad (13)$$

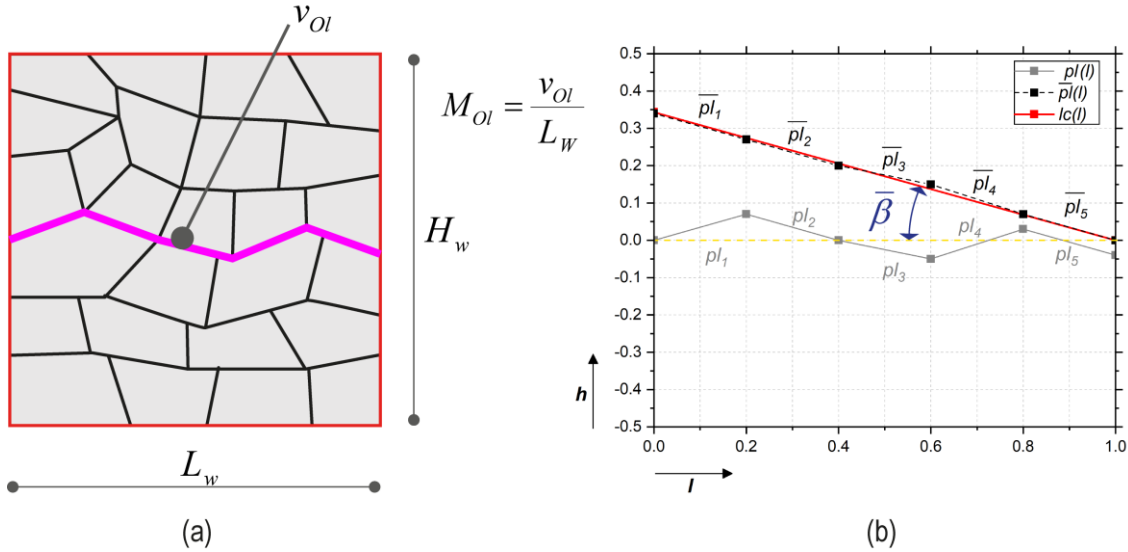
271 Such a parameter assumes a value of $M_{ol} = 1$ if horizontal and flat horizontal joints characterise the
 272 masonry pattern and $M_{ol} > 1$ in the case of uncoursed masonry.

273 Figure 6b shows a piecewise linear function $pl(l)$ that is representative of the traced line across the
 274 joints to evaluate M_{ol} , and a continuous linear function $lc(l)$, which is characterised by the same
 275 length of the piecewise function ($v_{ol} = \bar{v}_{ol}$) and a constant slope which is computed as follows:

$$276 \quad \tan(\bar{\beta}) = \frac{\sqrt{\bar{v}_{ol}^2 - L_w^2}}{L_w} \quad (14)$$

277 $\bar{\beta}$ assumes the physical meaning of an equivalent inclination of the masonry interfaces, and Eq. (14)
 278 permits its approximate computation just by measuring v_{ol} . Figure 6 also shows how the $lc(l)$ function

279 well simulates the transformed $pl(l) \rightarrow \bar{pl}(l)$, where in $\bar{pl}(l)$ all the pieces have the same length as
 280 $pl(l)$, but the absolute values of their own slopes are considered and joined in a continuous line.
 281 One can note that the computation of the slope of each piece ($\beta_1, \beta_2, \dots, \beta_n$) and the consequent
 282 assessment of the horizontal frictional component appear more rigorous from the physical perspective
 283 but inevitably increases practitioners' difficulties.



284 (a)
 285 Figure 6: Correction of frictional resistance taking masonry joints orientation into account: (a) Graphical
 286 interpretation of the horizontal line of minimum length M_{Ol} ; (b) Graphical interpretation of the equivalent
 287 interface inclination ($\bar{\beta}$).

288 Furthermore, the graphical construction reported in Figure 6b, allows to define the following
 289 equivalence:

$$290 \cos(\bar{\beta}) = L_w / \bar{v}_{Ol} = 1 / M_{Ol} \quad (15)$$

291 Hence multiplying by $\cos^2(\bar{\beta})$ or dividing by M_{Ol}^2 is mathematically equivalent.

292 In order to take into consideration the lower frictional resistance generated by the inclined interfaces,
 293 the definition of the equivalent α_b reported in Eq. (11) gets to:

$$294 \tan(\alpha_b) = \frac{(M_l - 1)}{M_{Ol}^2} \quad (16)$$

295 Eq.(16) can be adopted for all the masonry typologies described in Sections 3.1 and 3.2, taking into
 296 consideration the following statements:

$$M_l = M_l^{\min} \rightarrow \text{for rubble} \tag{17}$$

$$M_l = M_l^{URUL} \rightarrow \text{for regular and non-regular coursed squared}$$

Remark 5

As previously stated, the procedure implemented above provides an approximation in the computation of $\bar{\beta}$ but avoids the complication of individually decomposing the $pl(l)$ linear pieces and getting the slope of each piece.

Remark 6

According to Figure 5, the weight of the material column also has a parallel component to the interface, i.e., $F \cdot \sin(\beta)$, that increases or decreases the actual frictional resistance component to the horizontal inertial actions, depending on the inclination of the interface. Similarly, the friction force computed for an inclined joint also has a vertical component that in turn, may perform stabilising or destabilising work if the slope is positive or negative, respectively. From the practical perspective, and considering any rubble masonry pattern, interfaces having positive or negative slopes may be considered equivalent in number and length. Consequently, these two contributions are considered close to zero and thus neglected in the proposed formulation.

4 Algorithm description

The previous sections described an analytical formulation to quantify the equivalent maximum admissible crack angle for different masonry typologies. The following section reports the detailed description of the algorithm to calculate the horizontal load factor and the corresponding failure mechanism.

After a visual inspection, the user can take a picture of the RMPW and perform its vectorisation within a software CAD. Once identified the masonry typology, e.g., according to the definition provided in Sections 3.1 and 3.2, α_b can be computed according to Eq. (16).

If one refers to rubble masonry, for defining M_l^{\min} , the user must trace the minimum distance to connect two points in the up and down edges of the selected windows, whereas M_{Ol} should be evaluated at each pseudo-course, and the maximum value, acting as a penalty factor for α_b , has to be selected. On

322 the contrary, if the structure under investigation is characterised by regular or non regular coursed
 323 squared masonries, the structured path UP-RIGH-UP-LEFT drives the definition of the crack
 324 inclination upper threshold.

325 Once appropriately defined α_b , the constrained minimisation problem can be solved according to Eq.
 326 (4). Such a constrained optimisation problem has been mathematically implemented in a GHPython
 327 script [59,61]. The solution is achieved using a heuristic solver based on the Nelder-Mead method [62]
 328 that is able to refine the geometry of the macroblocks and search for the minimum value of the load
 329 multiplier λ within a few seconds. A schematic presentation of the algorithm is reported in Table T1.

330 Table 1: Description of the proposed method

Start	
1.	Visual inspection
2.	Identification of the masonry typology
3.	compute $\tan(\alpha_b) = \frac{(M_l - 1)}{M_{Ol}^2}$
3.1.	if masonry typology is regular and non-regular coursed squared, assume $M_l = M_l^{URUL}$
3.2.	if masonry typology is rubble, assume $M_l = M_l^{\min}$
4.	Define the failure mechanism parametrically
5.	Define the equilibrium equation according to the virtual work principle (Eq. (1))
6.	Solve the constrain minimisation problem according to Eq.(4)
7.	Get horizontal load factor and associated macro-block failure mechanism
End	

331 5 Brief DEM description

332 This study uses the discrete element method (DEM) formulated for rigid bodies to validate the proposed
 333 LA framework. The employed discontinuum-based approach was developed by Cundall [63] and
 334 extensively used to simulate the quasi-static and dynamic behaviour of masonry structures in the
 335 literature for the last several decades [64–66].

336 Briefly, the numerical procedure of DEM relies on the integration of translational and rotational
 337 equations of motion to predict the movements of distinct blocks along with their mechanical interactions
 338 with each other. The numerical solutions of the governing differential equations are obtained using the
 339 central difference method, in which the velocities are evaluated at the mid-intervals of the time step (Δt , $t^+ = t + \Delta t / 2$, $t^- = t - \Delta t / 2$). The explicit formulation of the equations of motion (written for the

341 centre of mass of an undamped rigid body) is given in Eq. (18) and Eq. (19), respectively for translation
 342 and rotation. Note that each rigid block, indicated by the subscript i , has six degrees of freedom: 3
 343 translational and 3 rotational in the three-dimensional space.

$$344 \quad \dot{\mathbf{u}}_i^{t+} = \dot{\mathbf{u}}_i^{t-} + \sum \mathbf{F}_i^t \frac{\Delta t}{m} \quad (18)$$

$$345 \quad \dot{\boldsymbol{\omega}}_i^{t+} = \dot{\boldsymbol{\omega}}_i^{t-} + \sum \mathbf{M}_i^t \frac{\Delta t}{I} \quad (19)$$

346 where $\dot{\mathbf{u}}$, $\dot{\boldsymbol{\omega}}$, m and I are the translational and angular velocity vectors, block mass and moment of
 347 inertia. Furthermore, $\sum \mathbf{F}_i^t$ and $\sum \mathbf{M}_i^t$ denote the unbalanced force vector, including the sum of the
 348 contact forces, self-weight, and applied forces, and moment vector consisting of the sum of moments
 349 produced by contact and applied forces, respectively. The quasi-static solutions are obtained from the
 350 given dynamic equations by adopting Cundall's local damping formulation [67]. The new velocities
 351 ($\dot{\mathbf{u}}_i^{t+}$, $\dot{\boldsymbol{\omega}}_i^{t+}$) are further utilised to update rigid block position and relative contact displacements (Δu_n ,
 352 Δu_s). The contact forces are computed via the linear/nonlinear springs defined in the normal and shear
 353 directions depending on the relative contact displacements (Figure 7). In this study, linear compression
 354 behaviour (no failure) with zero-tensile strength is considered to simulate dry-joint masonry behaviour
 355 in the normal direction, whereas the Coulomb-slip joint model is employed in the shear direction,
 356 requiring initial and residual friction coefficients (μ_0 , μ_{res}), shown in Figure 7. Through the explicit
 357 solution scheme of DEM, contact conditions are constantly monitored via a contact detection algorithm
 358 based on the common plane concept, explained in [68]. Therefore, possible failure modes such as joint
 359 opening, sliding, and total contact loss are captured during the analysis.

360 The normal and shear contact stresses (denoted as σ and τ , respectively) are calculated as elastic trials
 361 in an incremental format ($\Delta \sigma = k_n \Delta u_n$, $\Delta \tau = k_s \Delta u_s$) and added to the previous ones that are updated
 362 (if applicable) based on the adopted stress-displacement criteria. Finally, new contact stresses are
 363 multiplied with the associated contact area and included in the unbalanced force and moment equations
 364 to predict the new velocities as given earlier in Eq. (9).

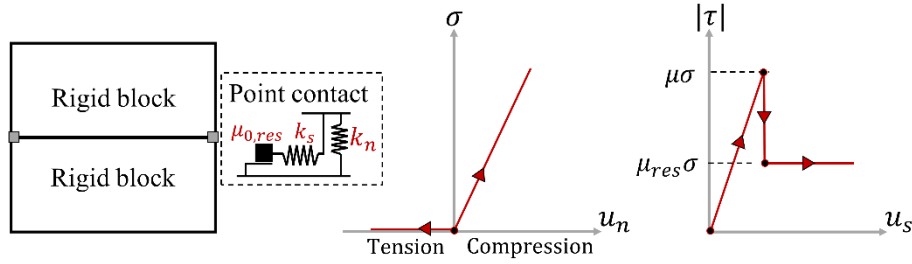


Figure 7: Illustration of point contact and defined contact constitutive laws in normal and shear directions.

The time-step Δt is adjusted to ensure numerical stability during the analysis since the central difference method provides only conditionally stable solutions. A commercial discrete element code, 3DEC developed by Itasca, is used throughout this research, which automatically provides a critical time step. Simply, the critical time step (Δt_c) is determined based on the minimum block mass (m_{\min}) and maximum contact stiffness ($k_{n,\max}$) in the discrete block system ($\Delta t_c = 0.2\sqrt{m_{\min}/k_{n,\max}}$). Hence, the mechanical behaviour of dry-joint masonry walls is simulated by a system of rigid blocks following the dynamic solution cycle of DEM, as explained in this section. Next, the applications of DEM-based simulations are presented and compared with the LA.

6 Validation by comparing LA and DEM results

The proposed analytical model is verified by investigating a number of case studies compared to advanced DEM simulations and numerical results arising from the literature. The first step in the validation scheme involves two sets of shear walls (each set is comprised of three masonry patterns characterised by an increasing degree of randomness). The masonry patterns used the generator available in Grasshopper plugin for Rhinoceros [59]. Finally, three real case studies of churches located in central Italy have been simulated, and results are compared with those reported in [69].

6.1 In-plane shear walls

These numerical simulations aim at verifying the capability of the proposed LA framework to predict the geometry of the collapse mechanism and the horizontal capacity of in-plane shear walls characterised by different masonry patterns ranging from regular and periodic to non-periodic. The analysed masonry patterns are illustrated in Figure 8. Here, SET-1 is characterised by unit aspect ratio $m = v/h = 0.75$, whereas SET-2 is characterised by unit aspect ratio $m = 0.50$. Also, case *a* is regular, case *b* is affected by courses having random heights and case *c* is non-periodic.

389 In DEM simulations, the loading condition is idealised in two steps: i) vertical actions are applied,
 390 including gravity loads and equilibrium is obtained; ii) then, a horizontal acceleration is applied
 391 incrementally. The mechanical properties utilised in discrete element models to simulate dry-joint
 392 masonry walls are listed in Table 2.

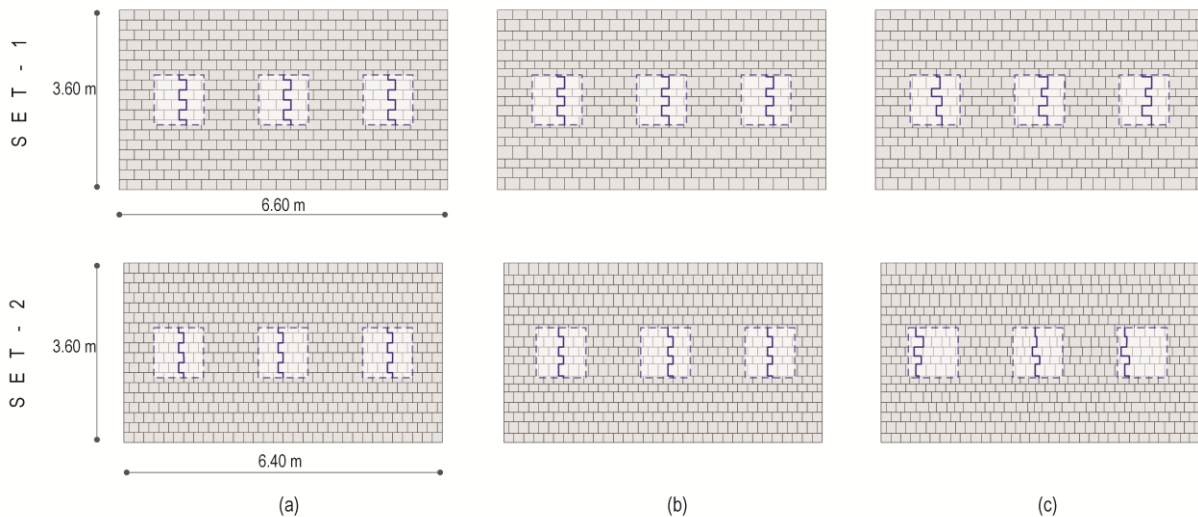
393 Table 2: Mechanical properties adopted in DEM simulations.

k_n [GPa/m]	k_s [GPa/m]	ρ [kg m ⁻³]	μ [-]
1.0	0.4	2000	0.70

394
 395 Figure 8 also represents the selection of three different RMPW adopted to evaluate the practical
 396 engineering parameters needed to apply the proposed analytical formulations, i.e., M_l and M_{ol} .
 397 Finally, Table 3 summarises the values of M_l and M_{ol} for all the simulated shear walls.

398 Table 3: Computation of M_l and M_{ol} for the structures under investigation.

	SET-1			SET-2		
	a	b	c	a	b	c
M_l	1.75	1.75	1.75±5%	1.50	1.50	1.53±7%
M_{ol}	1.00	1.00	1.00	1.00	1.00	1.00



400
 401 Figure 8: Shear-wall prototypes: SET-1 and SET-2.

402 In Figure 9, a comparison in terms of the load-displacement curve between the proposed analytical
 403 model and the DEM simulations is represented. The lateral forces, proportional to mass, are prescribed
 404 in discrete element models, gradually increasing until reaching failure. The blocks participating in the

collapse mechanism are determined once no quasi-static equilibrium is found in the computational model and the group of blocks reveals unbounded displacement under the given loading condition. Accordingly, the ultimate displacement is obtained based on the collapse mechanism and the associated turning point of the macro-block. LA results are reported for each representative window reported in Figure 8 involving in enveloped results the represented envelops. The proposed LA framework demonstrates its ability to carefully estimate the structural capacity of both periodic (SET-1a and SET-2a) and non-periodic masonry structures (SET-1b,c and SET-2b,c). This holds for maximum acceleration (or force capacity) and maximum displacement.

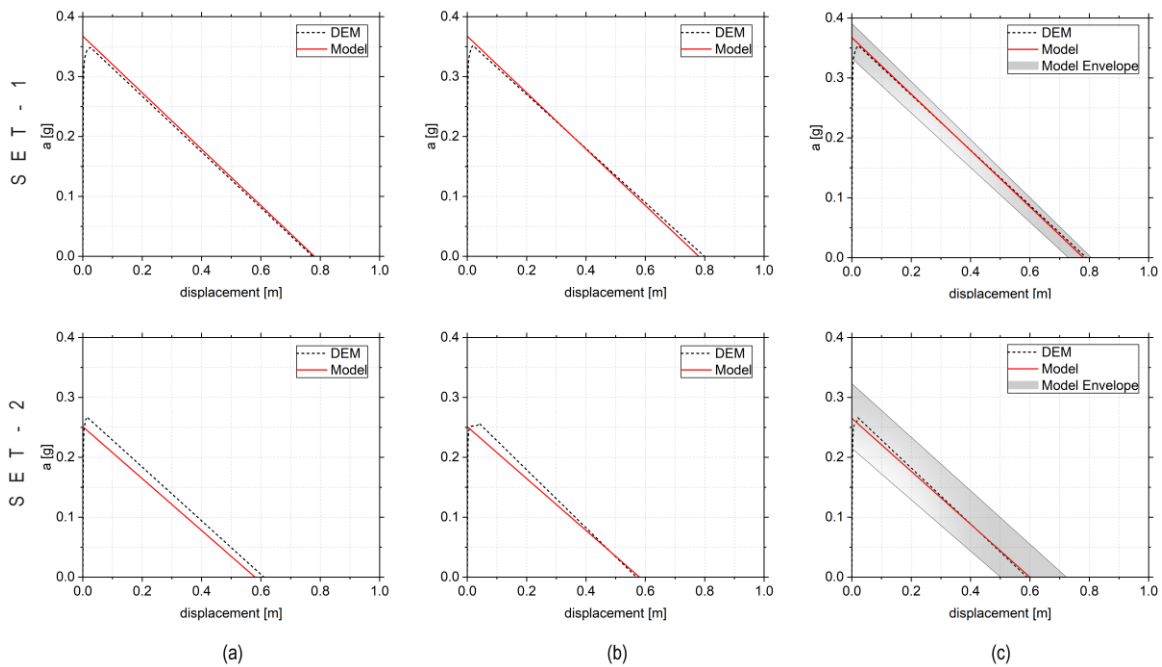


Figure 9: Pushover curves, measuring applied horizontal acceleration vs. horizontal displacement of the left corner: (a) regular, (b) curves having random heights, (c) non-periodic.

Regarding the collapse mechanisms, Figure 10 compares the geometry of the failure mechanisms between DEM (shaded in green) and the proposed LA framework (defined as a red triangle). There is an evident good agreement between the macroblock detected by the proposed model and the blocks involved in the collapse mechanisms obtained with DEM. The obtained results in terms of the loading displacement curves and collapse mechanisms demonstrate the adequacy of the proposed analytical model.

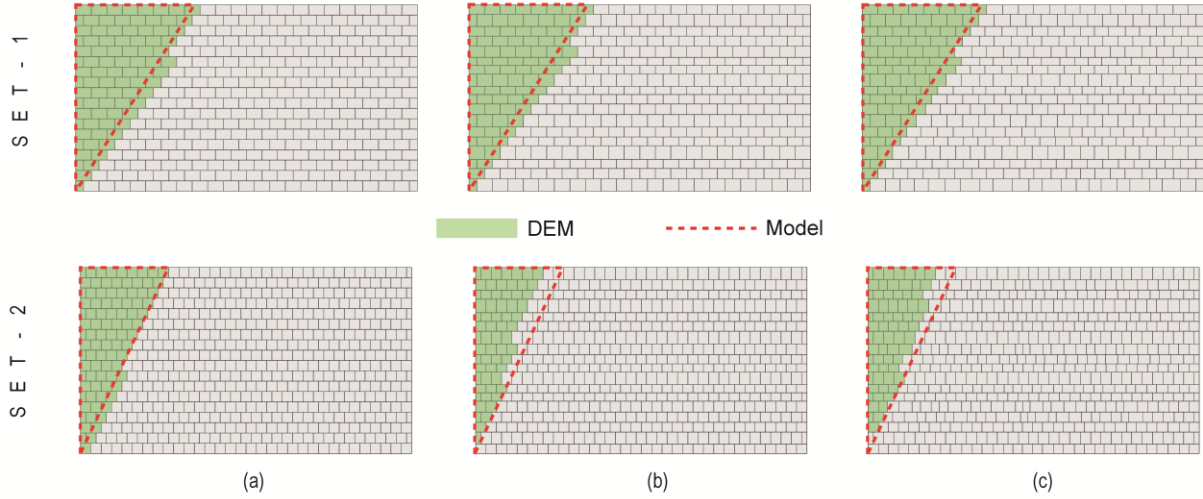


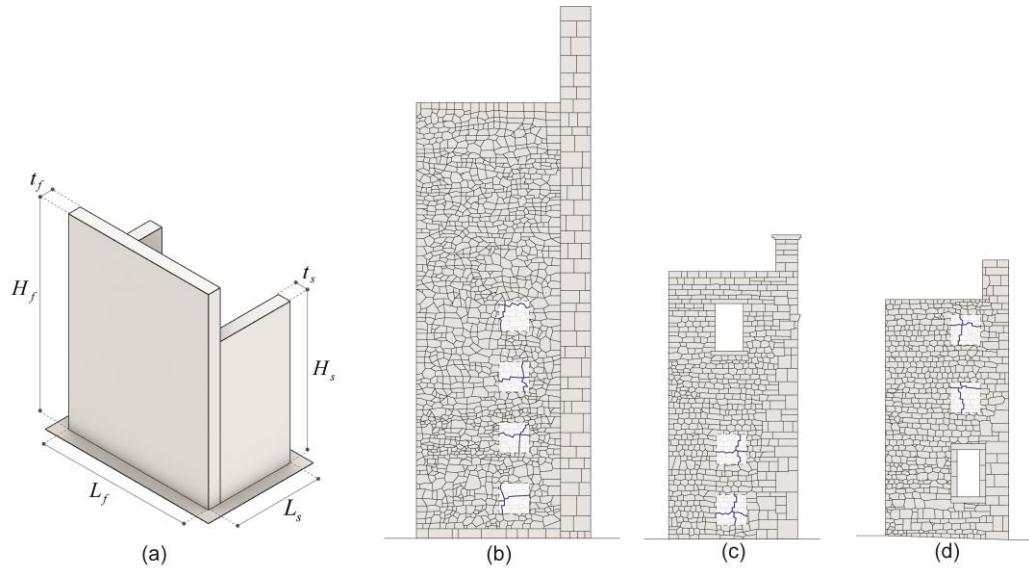
Figure 10: Comparison in terms of predicted failure mechanisms: DEM vs Model: : (a) regular, (b) courses having random heights, (c) non-periodic.

6.2 Case studies: Churches in central Italy

In this section, the proposed analytical model is applied to three single-nave churches belonging to the area surrounding the city of L'Aquila [69]. The churches under investigation are named: Church of S. Maria del Presepe (C1), Church S. Maria degli Angeli (C2) and Church S. Maria ad Cryptas (C3). The churches are analysed in a 2D framework, being the third dimension considered by providing the parts' thickness according to the sketch reported in Figure 11a. Table 4 lists the geometrical characteristics of the churches which are schematically represented in Figure 11. Furthermore, Figure 11b-d represents the real masonry patterns adopted for the simulation, which the authors [69] kindly provided to conduct the present research work. In the same sketches, the RMPWs adopted to evaluate M_l and M_{ol} are shown in white shading. These values are also listed in Table 4. The friction coefficient is taken constant for all the churches under investigation ($\mu = 0.57$).

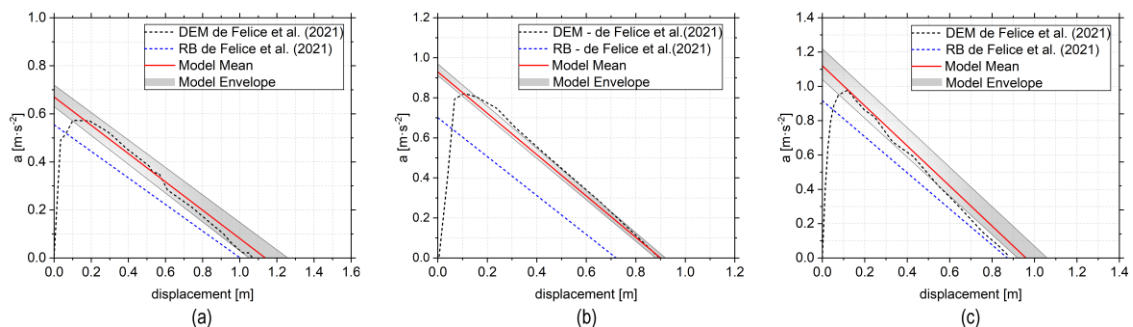
Table 4: Geometrical and mechanical properties of the churches under investigation.

	Façade				Side wall			Vert. length	Hor. Length
	L_f [m]	t_f [m]	h_f [m]	ρ [kg m ⁻³]	t_s [m]	h_s [m]	ρ [kg m ⁻³]	M_l [-]	M_{ol} [-]
C1	9.95	0.75	13.30	2200	1.40	10.40	2100	1.18±7%	1.18±5%
C2	10.00	0.70	10.00	2100	0.50	8.80	2000	1.31	1.08
C3	10.20	0.86	9.50	2100	1.00	7.90	2100	1.24	1.12



440 Figure 11: Churches under investigation: (a) geometrical configuration; (b) Church of S. Maria del Presepe (C1);
 441 (c) Church S. Maria degli Angeli (C2); (d) Church S. Maria ad Cryptas (C3).
 442

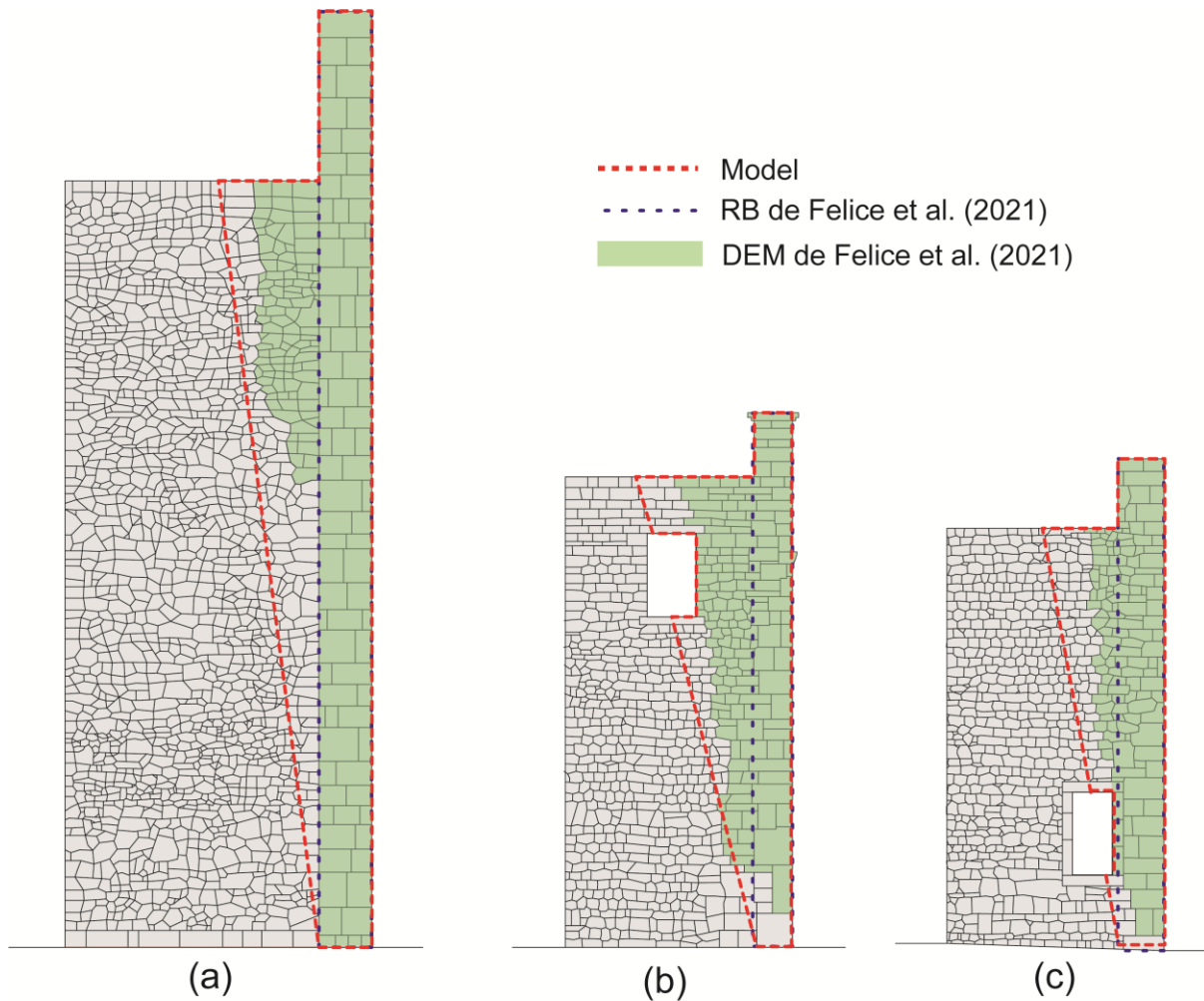
443 The comparisons in terms of load-displacement curves are reported in Figure 12, where the pushover
 444 curves regarding C1, C2 and C3 are represented in Figure 12 a, b and c, respectively. The proposed
 445 analytical model and DEM simulations from [64] have an excellent agreement in terms of both capacity
 446 and ultimate displacement. On the contrary, the Rigid Block (RB) model [69], accounting only for the
 447 façade overturning, always underestimate both structural capacity in terms of force and ultimate
 448 displacement of the structures under investigation.



449 Figure 12: Pushover curves, measuring applied horizontal acceleration vs. horizontal displacement: (a) Church of
 450 S. Maria del Presepe (C1), (b) Church S. Maria degli Angeli (C2), and (c) Church S. Maria ad Cryptas (C3).
 451

452 Figure 13 confirms the effectiveness of the proposed analytical model in terms of the predicted failure
 453 mechanism. The proposed model is able to adequately simulate the crack orientation across the
 454 sidewalls, which are characterised by rubble masonry patterns. In terms of the identification of the
 455 failure mechanism, the small difference between DEM and LA approach derives from the fact that in

456 [69], the authors only considered the rocking blocks and did not consider the blocks sliding in the failure
 457 mechanism, while in the LA the boundary of the failure mechanism is somewhere in between the
 458 rocking and the sliding failure line. Furthermore, in the case of the C2 and C3, the LA approach neglects
 459 the presence of the small openings. The investigation of the openings is out of the scope of this research
 460 work and will be investigated in future works.



461
 462 Figure 13: Comparison in terms of predicted failure mechanisms: DEM and RB vs Model: (a) Church of S. Maria
 463 del Presepe (C1), (b) Church S. Maria degli Angeli (C2), and (c) Church S. Maria ad Cryptas (C3).

464 7 Final remarks

465 This paper ambitiously presented a new formulation to assess the frictional resistance adopted in a
 466 macro-block LA formulation for historic masonry structures, specifically for the in-plane sliding-
 467 rocking failure mechanism. Such an approach takes advantages by the knowledge of practical
 468 engineering parameter, i.e., vertical and horizontal lines of minimum trace, for computing the frictional
 469 resistance in different masonry typologies. Compared with existing macro-block formulations for the

1
2 471 in-plane rocking-sliding failure mechanism, the proposed analytical model introduces the concept of
3 RMPW for the definition of the frictional resistance. Specifically, in [52,55], which accounts for regular
4 472 masonry patterns, the single unit blocks aspect ratio is adopted to evaluate the frictional resistance, see
5 Eq. (3). On the contrary, when different masonry typology characterises the structure under
6 473 investigation, a RMPW should be identified and Eq. (16) applied accordingly.

7
8
9 474 As a result, the analytical model can provide an estimation of the lateral capacity of a range of different
10 masonry walls and an accurate prediction of the geometry of the macro-block involved in the failure
11 475 mechanism. A refined DEM modelling has been adopted as a reference model for the validation of the
12 proposed approach. Furthermore, two real cases of study have been investigated (shear walls and
13 476 churches in central Italy), and the results compared well with the refined DEM models. The following
14 points summarise the main findings and contributions of the paper:
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- 23
24 481 • The proposed analytical model uses the definition of easy detectable geometrical parameters,
25 i.e., vertical and horizontal lines of minimum length.
26
27 482
- 28
29 483 • The analytical model is totally independent from mechanical parameters (as it is only based in
30 the geometry) and does not require computational power to get results, making this tool
31 484 particularly suitable for the assessment of a considerable number of structures in no time.
32
33 485
- 34
35 486 • The proposed analytical model can assess the structural performance of walls characterised by
36 different masonry patterns in a given wall, which occurs in several historical masonry structures
37 subjected to modification over the centuries or reconstruction after damage induced by past
38 487 earthquake events.
39
40 488
- 41
42 489 • The use of masonry indexes to classify masonry typologies and assess mechanical properties
43 will open new perspectives within the probabilistic assessment of historic masonry structures,
44
45 490 which is the objective of the work currently being developed by the authors.
46
47 491
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49 492

50
51
52 493 **Author contribution statement:**

53
54 494 **Marco Francesco Funari:** Conceptualisation, Methodology, Analytical Formulation, Writing-Original
55 draft preparation, Visualisation, Validation. **Bora Pulatsu:** Discrete element modelling, Writing-
56
57 495

1
2 496 Original draft preparation, Validation. **Simon Szabò**: Conceptualisation, Discrete element modelling,
3 Analytical Formulation. **Paulo B. Lourenço**: Writing-Reviewing and Editing, Supervision, Funding.
4

5 498 **Acknowledgements:**
6

7 499 The authors want to gratefully acknowledge Professor Gianmarco de Felice, Dr Francesca Gobin and
8
9
10 500 Rebecca Fugger, at Roma Tre University, Italy, for kindly sharing the masonry patterns of the churches
11
12 501 S. Maria del Presepe, S. Maria degli Angeli, and S. Maria ad Cryptas [69].
13
14

15 502 **Funding:**
16

17 503 This work was partly financed by FCT/MCTES through national funds (PIDDAC) under the R&D Unit
18
19 504 Institute for Sustainability and Innovation in Structural Engineering (ISISE), under reference
20
21 505 UIDB/04029/2020. This study has been partly funded by the STAND4HERITAGE project (New
22
23 506 Standards for Seismic Assessment of Built Cultural Heritage) that has received funding from the
24
25 507 European Research Council (ERC) under the European Union's Horizon 2020 research and innovation
26
27 508 programme (Grant agreement No. 833123), as an Advanced Grant.
28
29
30

31 509 **Conflict of interest:**
32

33
34 510 The authors declare that they have no known competing financial interests or personal relationships
35
36 511 that could have appeared to influence the work reported in this paper.
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The authors declare no conflict of interest